

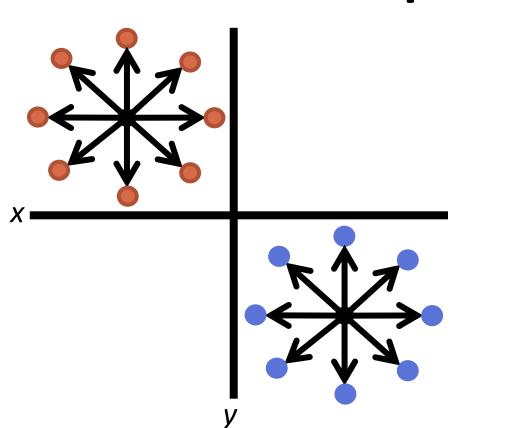
# The Influence of Change in Workspace on the Neural Representation of Movement

# Visual and Proprioceptive Workspaces

- Planning of motor movements involves the integration of multiple sensory inputs such as **visual** and **proprioceptive** (body posture) feedback
  - Visual and proprioceptive feedback have separable effects on neural firing (Stavisky 2018)
- **Visual** feedback (visual information to plan movement) and **proprioceptive** feedback (limb position) may be received from different possible workspaces, or physical regions in space
- How is the neural representation of movement impacted when visual and proprioceptive feedback are received from different workspaces?

# **Radial 8 Target Task**

### **2** Possible Workspaces



Combinations of Workspaces: V1P1 = 🕐 🖞 V1P2 = 🕐 🖞 V2P1 = 🔍 🖐 V2P2 = 💽 🖤

Sequence of Trials:

- Performed by rhesus monkey with
- Utah array implanted in M1 - Task performed with visual cue and arm movement synchronized to the same (V1P1 or V2P2) or different workspaces (V1P2 or V2P1) - Neural firing data analyzed during reach period when monkey moves
- arm from center to one of eight target directions

 $\bigcirc \Downarrow \rightarrow \bigcirc \Downarrow \rightarrow \bigcirc \Downarrow \rightarrow \bigcirc \checkmark$ N = 8 N = 8N = 8

## **Creating a Naïve Bayes Classifier**

- Create a Naïve Bayes Classifier to decode neural firing rates under different (visual and proprioceptive) workspace conditions
- Accuracy of decoder under different conditions indicates which type of input (visual and/or proprioceptive) is most important to decoder
- Reveals which type of information may have a greater impact on the neural representation of movement

### Naïve Bayes Classifier: - Finds class with highest computed likelihood, given

some input Likelihood of class Y:

$$I(Y) = \sum_{i=1}^{n} x_i \log(\lambda_i) - \lambda_i$$

n = neurons  $x_i$  = firing rate of neuron i  $\lambda_i$  = mean firing rate of neuron i given class Y Poisson distribution used to model neuron firing rates given class Y

Accuracy Differentiating Targets		
All Trials (N=1448)	55.8 %	
V1P1 (N=360)	76.7 %	
V1P2 (N=360)	74.4 %	
V2P1 (N=360)	76.9 %	
V2P2 (N=368)	76.1 %	

Chance: 12.5%

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### **Visual Target Decoder**

- **Input**: Neural firing rates
- **Output Class**: Estimated target angle
  - from Radial 8 Target Task

Accuracy Differentiating Targets	
Visual Workspace 1 (N=720)	56
Visual Workspace 2 (N=728)	55
Chancold 12 5%	

Chance: 12.5%

# Separation by proprioceptive workspace improves accuracy

**Proprioceptive Target Decoder** 

- **Input**: Neural firing rates
- **Output Class**: Estimated target angle

from Radial 8 Target Task



Accuracy Differentiating Targets	
Proprioceptive Workspace 1 (N=720)	78
Proprioceptive Workspace 2 (N=728)	77

Chance: 12.5%

# Visual workspace confused more than proprioceptive workspace

### Workspace Decoder

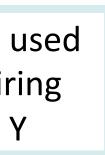
- **Input**: Neural firing rates
- **Output Class**: Estimated workspaces

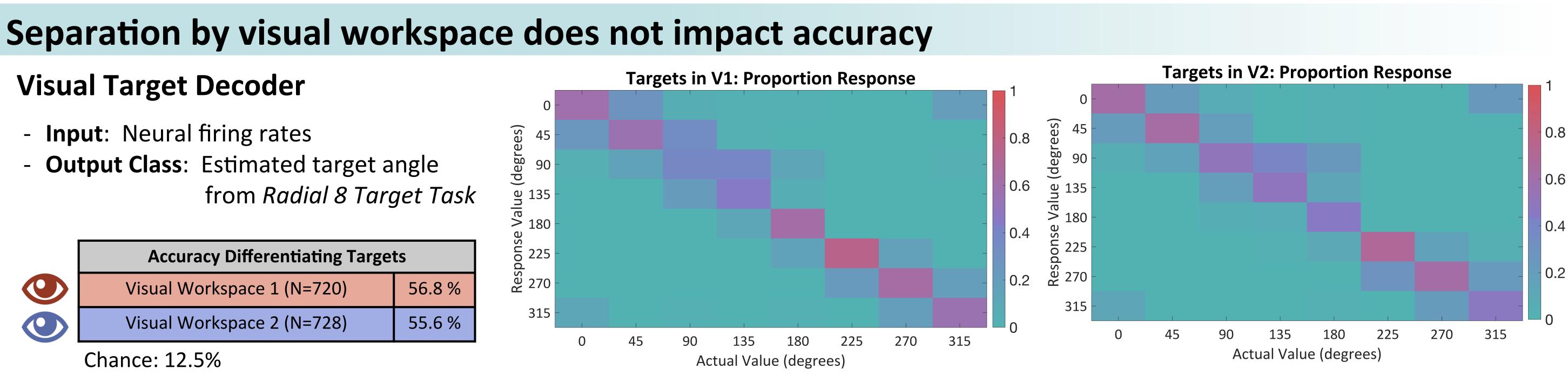
Chance: 25%
Chance: 50%
Chance: 50%

Accuracy Differentiating W
All Workspaces (n=1448)
Proprioceptive Workspaces (n=
Visual Workspaces (n=1448

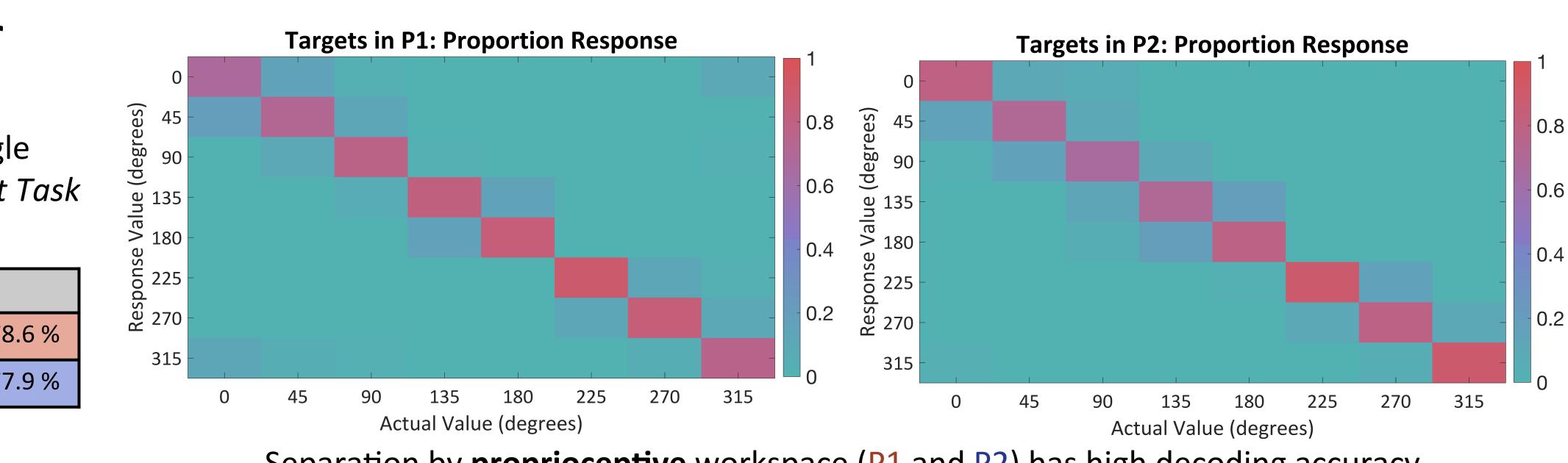
### Discussion

- **proprioceptive** feedback if movement performed in different workspaces

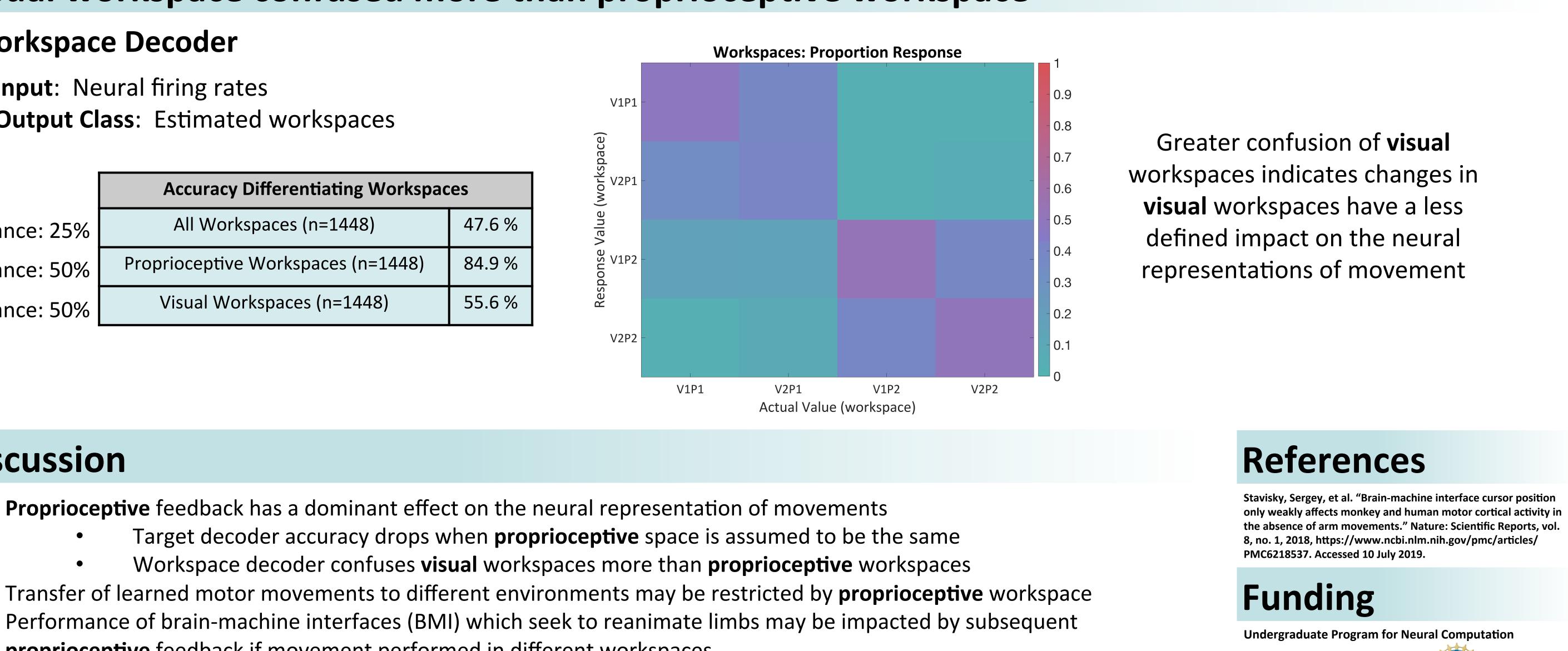




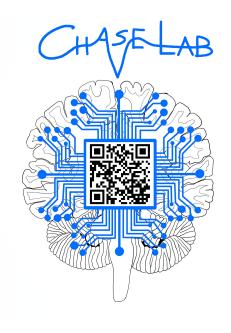
Separation by **visual** workspace (V1 and V2) has low decoding accuracy because **visual** workspace does not account for large changes in neural firing

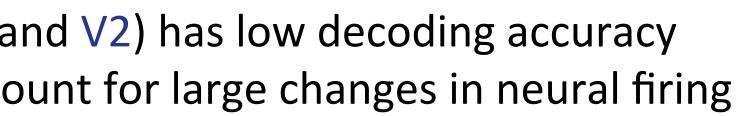


Separation by **proprioceptive** workspace (P1 and P2) has high decoding accuracy because **proprioceptive** workspace accounts for large changes in neural firing



**Proprioceptive** feedback has a dominant effect on the neural representation of movements Target decoder accuracy drops when **proprioceptive** space is assumed to be the same Workspace decoder confuses visual workspaces more than proprioceptive workspaces





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