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Loss Aversion and Inhibition in Dynamical Models of Multi-Alternative Choice

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Abstract

We examine loss aversion and inhibition among alternatives in models of the similarity, compromise, and attraction effects that arise in choosing among three alternatives differing on two attributes. Roe, Busemeyer and Townsend (2001) have proposed a linear model in which effects previously attributed to loss aversion (Tversky & Kahneman, 1991) arise from similarity-dependent inhibitory interactions among alternatives. We argue that there are other reasons to maintain loss-aversion and point out difficulties with the linear model. We incorporate loss aversion into an alternative non-linear model (Usher & McClelland, 2001) that relies on inhibition independent of similarity among alternatives. The model accounts for the three effects and makes testable predictions contrasting with those of the Roe et al (2001) model.

Loss Aversion and Inhibition in Dynamical Models of Multi-Alternative Choice

Several interesting empirical discoveries have emerged from studies of how people choose between several objects that differ on two or more attributes. For example, someone might be given a choice among three automobiles, varying in performance quality and driving economy (Roe et al., 2001). Experimental investigations of human decision making in such multi-alternative, multi-attribute situations have revealed a series of effects that raise challenges for traditional theories of rational choice. These traditional theories are based on the normative principle of *independence of irrelevant alternatives* (Debreu, 1960), which states that the relative preference of any two alternatives is independent of all other alternatives. Despite the intuitive appeal of this principle, a number of violations have been discovered. Below we describe three central effects that illustrate these violations, called the *similarity*, the *attraction* and the *compromise* effects (Roe et al., 2001). The situations all arise in choice among three alternatives defined by two attributes, as in the car example above. A graphical representation of the positions of the various alternatives within the two dimensional space defined by the position of each alternative with respect to its value or attractiveness on each of the attributes is provided in Figure 1.

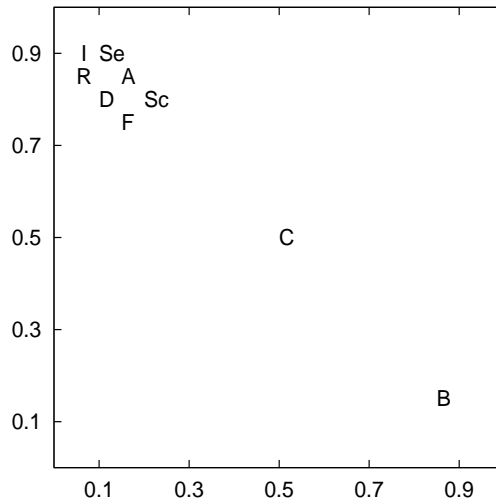


Figure 1: Illustration of choice alternatives characterized by their values on two dimensions associated with the attributes that distinguish the alternatives. The alternatives might be automobiles and the attributes might be performance quality and driving economy. Each alternative is defined as a point in this two dimensional space, consisting of a value or attractiveness with respect to each attribute within the normalized interval $(0, 1)$, corresponding to the attractiveness of the alternative with respect to the attribute. The negative diagonal in the figure corresponds to the indifference line along which there is a perfect trade-off of attractiveness, so that when the choice is restricted to two alternatives on this line each has a choice probability of 0.5.

Most cases we will consider involve the alternatives A and B in Figure 1, preselected to be of equal binary preference, such that $P(A|A, B) = P(B|A, B)$, that is, the probability of choosing A equals the probability of

choosing B when these are the only available choices. Each case also involves a single additional alternative. All points on the negative diagonal in the figure (the indifference line) are of equal binary preference; alternatives on this line, including S_e , S_c , and C are *indifferent* alternatives with respect to A and B . All those below the line (such as I) are *inferior* alternatives of lesser binary preference relative to alternatives on the indifference line. An inferior alternative with a value less than another on one dimension and less than or equal to it on the other dimension is *dominated* by that alternative (e.g., D , R , F are dominated by A).

The similarity effect. This effect arises when an indifferent competitive option similar to A , such as either S_e or S_c (the subscripts e and c correspond to extreme and compromise respectively, relative to the options A and B) in Figure 1, is added to the set of alternatives. The added alternative results in a change of the choice probability between A and B , in favor of the dissimilar alternative ($P(B|A, B, S_x) > P(A|A, B, S_x)$, $x \in c, e$, Tversky, 1972; Sjöberg, 1977). This effect violates the principle that an irrelevant alternative (S_x) should not influence the relative probability of choice between a specific pair of alternatives (A and B).

Attraction effect. When the third option (such as D , R or F) is dominated by the similar alternative (A), its introduction can enhance the likelihood of choosing A over B , $P(A|A, B, D) > P(B|A, B, D)$ (Huber, Payne & Puto, 1982; Simonson, 1989). In some cases one even finds that adding the choice option to the response set increases the likelihood of choosing A compared to the situation in which B was the only alternative (e.g., $(P(A|A, B, D) > P(A|A, B))$). Such a finding violates the so-called *regularity* principle, which is implied by a large class of random utility models (see e.g., Marley, 1989). A further distinction is sometimes made between two types of dominated options R and F (called *range* and *frequency* decoys, respectively). The attraction effect has been shown to be larger with range decoys (Huber et al. 1982).

Compromise effect. This effect arises when the third alternative (such as C in Figure 1) is an indifferent one positioned half way between A and B . In this condition, C tends to win over A and B ($P(C|A, B, C) > P(A|A, B, C) = P(B|A, B, C)$, Simonson, 1989; Tversky & Simonson, 1993).

An intensive effort to provide a causal explanation of choice behavior that meets these challenges was undertaken by Tversky and colleagues (Tversky, 1972; Tversky & Kahneman, 1991; Tversky & Simonson, 1993). Consistent with the theory of choice under uncertainty (Kahneman & Tversky, 1979; 1984), Tversky's account of multi-alternative, multi-attribute preference is based on two central tenets: i) Options are evaluated relative to a reference frame and ii) the value function for gains and losses (advantages and disadvantages relative to the reference) is S-shaped and asymmetric, with a higher slope in the loss domain that conforms to the principle of *loss aversion* (Tversky & Kahneman, 1991; Tversky & Simonson, 1993). Within this model, called the *context dependent advantage* model, violations of the independence of irrelevant alternatives principle occur because decision-makers treat all the alternatives in the option-set as reference points in the evaluation of each option.

Although the context-dependent advantage model accounts for the attraction and compromise effects, Roe, Busemeyer and Townsend (2001) have recently shown that it fails to account for the similarity effect.

Interestingly, one of the first models of multi-attribute, multi-alternative choice, the *elimination by aspects* (EBA) model of Tversky (1972), explains the similarity effect, but not the attraction and compromise effects. In their recent article, Roe et al. have shown that a model for multi-alternative, multi-attribute choice, based on their decision-field theory (DFT)(Busemeyer & Townsend, 1993) accounts for all three effects. The model shares a property of the EBA model (Tversky, 1972) in assuming that decision-makers attend to only one of the attributes (or aspects) that differentiate the alternatives at a time, sampling the aspects at random.

The model also shares with the context-dependent advantage model the principle that the input into the choice evaluation is driven by *valances*, which are computed contrasts between the options. However, the Roe et al. model differs from the context-dependent advantage model in that it does not rely on nonlinear and asymmetric value functions for gains and losses. As we discuss in detail below, it relies instead on the use of a distance-dependent lateral inhibition mechanism within a linear dynamical system where alternatives with negative activations can boost the activation of similar competitors. This is perhaps the most interesting and provocative aspect of their model, since it suggests that apparent loss-aversion on the part of human subjects may be an emergent property of decision dynamics. For this reason, we will refer to the Roe et al model as the decision field theory model with distance-dependent inhibition (DFT_{DDI}).

In the present article, we offer an alternative to the DFT_{DDI} model that also accounts simultaneously for the similarity, attraction, and compromise effects. Our approach, which arises within our leaky-competing accumulator (LCA) model of perceptual choice (Usher & McClelland, 2001), shares many of the same principles of the DFT_{DDI} model, but differs from it in its assumptions about competitive interactions among alternatives and loss aversion. Two considerations motivate our alternative treatment of these issues. First, we will argue that the mechanism used by Roe et al. does not provide a unified account for all the situations where loss-aversion is found in decision-making (Tversky & Kahneman, 1991). Second, the attraction effect arises in the DFT_{DDI} model because it relies on a completely linear dynamical system in which activations below 0 are allowed to propagate to other units, thereby allowing a dominated alternative to boost the activation of a similar competitor via an “inhibitory” (i.e., negative-valued) connection. As we will also review below, the propagation of activations below 0 is not allowed in the LCA model or in many other models of perceptual choice because it has undesired computational consequences. We address these considerations by showing that it is possible to account for the three effects in a version of a leaky competing accumulator model that incorporates stochastic attention switching and relies directly on loss aversion instead of distance-dependent inhibition and propagation of negated inhibition.

The model we propose addresses the point raised by Roe et al that no single model incorporating loss aversion has heretofore simultaneously addressed the similarity effect together with the attraction and compromise effects. By retaining the core principles of the leaky-competing accumulator model is also builds a bridge between efforts to understand multi-alternative, multi-attribute choice on the one hand and perceptual identification on the other. As we show below, the model also makes distinct predictions from the DFT_{DDI}

model, allowing for clear tests to be carried out that will discriminate between these alternative approaches. In what follows we first review the DFT_{DDI} model, and then consider how it accounts for the three effects. We go on to present in more detail some reactions to this account, thereby motivating our alternative account based on the use of leaky competing accumulators, attention switching, and loss aversion. We then proceed to demonstrate how the model accounts for the similarity, attraction, and compromise effects. Finally, we discuss the contrasting predictions made by the different models, indicating how they can be distinguished by future experiments.

The DFT_{DDI} Model

The DFT_{DDI} model was developed within decision field theory (DFT), which has been successfully applied to a wide range of decision-making situations (Busemeyer & Townsend, 1993; Diederich, 1997, 2003; Diederich & Busemeyer, 1999; Roe et al. 2001; Busemeyer & Townsend, 1995; for a survey see Busemeyer & Diederich, 2002). As with some other DFT models, it relies on leaky integration of information. As the authors noted, the model can be viewed as a neural network with four layers. The first layer corresponds to the input attribute values, which feed via weights into units at level 2 that correspond to the two choice alternatives. An attentional mechanism stochastically selects between the attribute units, so that only one attribute (determined randomly) provides input to level 2 at each time step. Level 3 computes valences for each by subtracting the average level 2 activation of the two other alternatives from its own level 2 activation. As the attention switches between the attributes, the valences vacillate from positive to negative values. Level 4 is the choice layer, which performs a leaky integration of the varying input from level 3 (the leaky integration is sometimes called an *Ornstein-Uhlenbeck diffusion process*.¹, and is used in several other models including those of Busemeyer and Townsend (1993), Diederich (1997), and Usher and McClelland (2001). Competition between the options occurs at level 4, mediated by bi-directional inhibitory connections with strengths that are assumed to be distance dependent. That is, the strengths of the inhibitory connections among units in the fourth layer decrease as the distance between them, in the attribute space shown in Figure 1, increases. To support this, it is suggested that an inhibition function that decreases monotonically with distance (dissimilarity) is consistent with the computation of contrast in early sensory processing. Two different rules for selecting a response are considered: According to the external stopping rule, some event independent of the state of the decision making process determines the time at which the choice is made, and the choice unit that has the highest activation at the given time is selected. According to the internal stopping rule, a unit is selected if it is the first to reach a response criterion. Roe et al. indicate that both approaches produce similar results. Since the external stopping rule is the basis of their main graphs, we will focus on that case in our own simulations.

¹A diffusion process is a statistical process that tracks the evolution through time of a random variable subjected to perturbation by noise. The standard or *Weiner* diffusion process describes a perfect integration of the perturbations, such that they are simply summed over time to determine the state of the variable. In the OU-diffusion, the random variable is also affected by a decay term that attracts the variable towards a baseline with a force proportional to its deviation from it.

Central to understanding the way in which the DFT_{DDI} model accounts for the similarity and compromise effects is the pattern of correlation among the activations of the response units. In cases where three alternatives on the indifference line are used, the net input to each alternative always averages out to 0. By itself, this would lead to equal choice among all three alternatives, if it were not for the effects of correlations. The more two units are temporally correlated in their activation dynamics, the more they come to share the same opportunities for choice, leading to a choice advantage for alternatives that are relatively uncorrelated with other alternatives. In conjunction with the random alternation of attention between the attributes, this leads, as in the EBA model, to the similarity effect. Because of the attentional switching, the activations of similar options such A and a similar alternative (S_e or S_c) tend to rise and fall together, as they are activated and deactivated together by the supporting attributes. When the stopping rule indicates it is time to make a choice, it will usually be the case that the correlated alternatives are both more active than the other, uncorrelated one, or the correlated alternatives will both be less active. In the first case, they split between them the opportunity to be chosen, while in the second case the uncorrelated alternative will be chosen, thereby producing the similarity effect. The compromise effect is also explained with regard to correlations between activations of choice units. This time, however, this correlation is induced, not by the alternating attribute input, but by the distance dependent inhibition. The inhibition is higher between the middle or compromise option C and the two more extreme alternatives A and B than it is between the extreme alternatives A and B themselves. As a result, the activation of the compromise alternative becomes anti-correlated with the activation of the two extreme alternatives, thereby leading them to become correlated with each other. Once again choice probability is split between the correlated alternatives, resulting in a compromise advantage.

The DFT_{DDI} model gives a very different explanation for the attraction effect. What happens in the model is that the dominated alternative D has a negative valance input (averaged over the dimensions). As a result, the activation of the unit for this alternative quickly becomes negative. At this point, this alternative sends positive activation to the other alternatives. This is because a negative activation, when multiplied by a negative connection weight, produces a positive resulting activation. The effect of this negative activation on the similar alternative A is greater than the effect on B due to the distance dependence. Thus, A receives more boosting than B , accounting for the attraction effect.

Reactions to the DFT_{DDI} Account

The DFT_{DDI} model accounts for a set of phenomena that have previously been thought to require the use of a loss-averse value function. As such, it is intriguing and provocative. Loss-averse behavior arises in the model as an emergent consequence of a dynamic decision making process based on principles the authors attribute to the underlying neural computation. Since much of our own previous work explores emergent consequences of neural networks (in place, for example, of explicit rules, as in Rumelhart &

McClelland, 1986), we find ourselves quite sympathetic to the approach. Yet in this particular case, it may be worth considering further the merits of retaining loss aversion as an explicit contributing factor in explaining human choice behavior. We first summarize, following Tversky and Kahneman (1991), the need for loss-aversion in multi-attribute choice, pointing out that the ‘emergent’ loss-aversion produced by distant-dependent activation by negated inhibition does not cover all choice situations exhibiting this property. While other features might be introduced into the DFT to address the remaining situations, thus far the coverage is incomplete and the mechanisms that have been proposed are not without difficulties. We then examine the use of distance-dependent inhibition by negated activation itself, suggesting reasons why we see this mechanism as problematic. That background will lead us to present our own model, similar to the DFT_{DDI} , but incorporating loss aversion explicitly rather than relying on distant-dependent activation by negated inhibition. This is consistent with Tversky and Kahneman’s position of loss aversion as a basic principle grounded in the fact that “the asymmetry of pain and pleasure is the ultimate justification of loss aversion in choice.” (Tversky & Kahneman, 1991, p. 1057).

Loss-aversion in Multi-Attribute Choice

A large number of studies indicate that loss-aversion is a general principle underlying decision-making in a wide range of contexts. We focus here on studies involving choice between options characterized by several attributes, ignoring studies of risk and monetary equivalents (but see, e.g., Kahneman & Tversky, 2000). Consider the following three situations.

The endowment/status quo effect: Rather fight than switch? Three groups of participants are offered a choice between two objects of roughly equal value (a mug and a chocolate bar), labeled here as A and B . One group is first offered the A -object and then the option to exchange it for the B -object. The second group is offered the B object followed by the option to exchange it for A . The control group are simply offered a choice between the two objects. The results reported by Knetsch (1989) are striking. Whereas the control participants chose the two objects in roughly equal fractions (56% vs 44%), 90% of the participants in either of the groups that were first offered one of the objects prefer to keep it rather than exchange it for the other one (see also Samuelson & Zeckhauser, 1988). This effect is directly explained by Tversky and Kahneman by appealing to the loss-aversion function. Because losses are weighted more than gains, participants who evaluate their choices with the already-owned object serving as the reference point decline the exchange. For the control participants the values may be computed either relative to the neutral reference (Tversky & Kahneman, 1991), or each option can be used as a reference for the other options (Tversky & Simonson, 1993). In either case, there is no reference bias, consistent with the nearly equal choice fractions in this case.

Preference for improvements over trade-offs: Participants are offered the possibility to exchange an option they just received (the reference), for one of two more valuable options of roughly equal value, A and B . For half of the participants, the reference is similar to, but of less value than, A (e.g., option F in Figure 1), while for the other half, the reference is similar to but of lesser value than B . The majority of

participants (more than 65%) prefer to exchange the reference object for the similar option that dominates it (Tversky & Kahneman, 1991). This follows under the principle that losses are weighted more heavily than gains, since the similar choice involves a small improvement, while the dissimilar choice involves a trade-off involving a large gain outweighed by a large loss.

Advantages and disadvantages: Small ones are preferred over large. Participants imagine making a choice between two items (jobs), A and B , to replace a reference item (a present job that is being terminated). Again, for half of the participants, the reference is similar to A , while for the other half it is similar to B . Unlike the case just considered, the reference is not a dominated option. Instead it is a relatively extreme option on the indifference line with the similar and dissimilar alternatives. For example, the reference similar to A would correspond to S_e in Figure 1. Also, note that the reference itself cannot be chosen; it is described as no longer available. Even in this case, most participants (about 70%) choose the option similar to the reference. Tversky and Kahneman explain this finding, too, by appeal to loss-aversion. The similar option involves small gains and losses, while the distant one involves large gains and losses. Since losses are weighted more than the corresponding gains, the combination of the larger gain and loss is less preferred than the combination of the smaller gain and loss.

In summary, the three effects described above, along with the compromise and attraction effects, are all directly explained by loss aversion. We have already discussed how the compromise and attractions affects can be addressed in the DFT_{DDI} model; we now consider the three additional effects. The model can address the improvement-tradeoff effect, without assuming an explicit asymmetric value-function as proposed by Tversky and Kahneman (1991), since it can be viewed simply as an instance of the attraction effect. The dominated reference option boosts the activation of the similar option, via distance-dependent activation by negated inhibition. However, this mechanism cannot account for the endowment/status-quo effect. Distance-dependent activation by negated inhibition cannot be responsible for the tendency to prefer the owned object: since distance is symmetric, the two objects must inhibit each other to an equal extent. Instead some other principle must be applied to address loss-aversion in this situation. Busemeyer and Townsend (1993) account for this effect by proposing that the initial preference state for the owned alternative is greater than that for the other, not owned, alternative. While such an account deserves consideration, it is worth noting that justification for assuming that there is an initial preference for the owned alternative is not clear, unless one appeals to something very much like loss aversion. Even as an implementation of loss aversion, the proposed mechanism may not be robust enough to account for all instances of the effect. The impact of the initial preference will diminish and eventually vanish as a decision maker deliberates (Busemeyer & Townsend, 1993).² Thus, the appeal to an initial preference for the owned object may not account for the effect in situations where the subjects are given time to deliberate before deciding, as in Knetch and Sinden (1984). In their experiment, participants were first given a gift (a lottery ticket) and were then told that they would

²For example, the effect of the initial preference vanishes over time in the simulation illustrated in Figure 7 of Busemeyer & Townsend (1993), where the response-criterion is assumed to increase with time-deadline. Even if the deadline was not increased, any effects of initial preference will necessarily be located at the fast part of the RT-distribution.

have the option to keep the gift (and play in the lottery) or exchange it for a cash amount. A control group was offered the option of buying the lottery ticket for the same cash amount. Subjects were then invited to leave the room in which the choice was offered and to stop at a 'cash desk' outside to discuss the options before finalizing their decision. This procedure was adopted so that participants would not influence each other in their choices. However, it also seems to ensure that the participants are given considerable time to deliberate, which should allow the initial preference state to dissipate. Similar considerations arise in an intriguing example of the status quo effect lasting over several years in choices among alternative car insurance policies in New Jersey and Pennsylvania (Kahneman, Knetch & Thaler, 1991). These problems do not arise in the approach we advocate, in which loss aversion operates to provide a stable preference for the previously owned alternative, without erosion of the effect over time.

Finally, let us consider the advantage/disadvantage situation. Here the reference is not dominated by the other options, as it is in the improvement-tradeoff case, so its valence is not generally negative and does not boost the activation of the similar option by negated inhibition. Moreover, the previously-held job is not available as a choice alternative, so it is not clear that it should actually be treated as an option in the decision process. If it were treated as an option, then for consistency with the DFT_{DDI} model's account of the status quo effect, this option should receive an initial positive preference, but this would if anything lead to inhibition of the similar option. In the absence of such an initial positive preference, the correlation mechanism in the DFT_{DDI} could operate to influence choices, but in this case it would if anything reduce, rather than enhance, choices of the similar alternative, as in the similarity effect.³ Thus, if the DFT_{DDI} theory is to account for the effect, it would appear that yet another principle will have to be added to address the data.⁴

In summary, work within the decision field theory does not rely on asymmetric value functions and has instead offered a range of different mechanisms to account for several different scenarios that have been used to motivate a direct appeal to the principle of loss aversion. Thus, distance-dependent activation by negated inhibition, only addresses some of the effects. We now consider further difficulties with this mechanism.

Treatment of Distance-Dependency in DFT_{DDI}

One feature of the distance dependent inhibition assumption used in Roe et al (2001) is that no specific function has been introduced that specifies the exact way in which inhibition varies with distance between alternatives. This approach has the advantage of avoiding unnecessary over-specification. At the same

³Exactly what effect the inclusion of an alternative that cannot be chosen might have on preferences is not clear. Two possibilities present themselves. (1) When it comes time to choose, only the available alternatives are considered. In this situation, the correlations between the reference object and the similar alternative would not influence choice probabilities. (2) When it comes time to choose, all participating options are considered, but if an unavailable option is chosen, the choice is rejected, so that a second choice must be made. This would tend to produce a disadvantage for the similar option.

⁴Busemeyer and Johnson (2003) have suggested that the DFT_{DDI} can account for this situation by incorporating a third attribute called 'availability' to distinguish the reference from the available options. By virtue of its unavailability, the reference would have a lower overall valence than the other alternatives, causing it to become dominated and thereby allowing it to activate the similar alternative by negated inhibition. This assumption is not necessary in our approach and we think it raises additional difficulties. Space constraints prevent a fuller consideration.

time, it introduces considerable model freedom, and there are reasons for uncertainty about the existence of a satisfactory distance dependent function that obeys the stated principle: “The basic idea is that the strength of the lateral interconnection between a pair of options is a decreasing function of the distance between the two options” (Roe et al, 2001, p. 374). In the main simulations of the similarity, attraction, and compromise effects presented in Figures 4, 7, 12 in Roe et al, the value of the inhibition between options A and similar options (S_e , and D) was set to the same value as that between options A and the compromise option C (.025); lesser inhibition was only used for more distant alternatives (the strength of inhibition between B and any of A , S_e , D , R , and F was set to 0.001). Thus the inhibition between alternatives A and C is no less than that between alternative A and more proximal options (S , D), even though alternative C is shown as lying quite a bit farther from A than any of the other mentioned alternatives (Figure 1). The absolute differences used in the Figure are arbitrary, and the compromise and similarity effects are generally obtained in quite distinct experiments. Thus we cannot be sure that alternative C in compromise studies is in fact less similar to the A and B alternatives used there than the S alternatives in similarity studies are to the A and B alternatives that they employ. Even so, it is potentially problematic for the DFT_{DDI} account if it could only produce the right magnitudes for the various effects when the compromise alternative C is effectively as close to both A and B as A is to both of the S alternatives and the various dominated alternatives D , R , and F .

In this context it is worth noting that there is a tension in the model between the accounts it offers for the similarity and the compromise effects. The similarity effect decreases with the strength of the lateral inhibition between the similar alternatives, while the compromise effect increases with strength of lateral inhibition between the compromise and non-compromise alternatives. Thus, it is not clear that it will be possible to account for the actual magnitudes of the compromise and similarity effects if the alternatives in the compromise situation are far enough apart to mandate lower inhibition than that operating between the similar alternatives.

The points we have made in this section do not count as conclusive arguments against the DFT_{DDI} approach. It may turn out to be possible to specify a particular, consistently-applied function relating distance to strength of inhibition that allows the similarity, compromise, and attraction effects to be captured at the same time. However, the DFT_{DDI} approach combines the use of a distance-dependent inhibition function with the propagation of negative activation to account for the attraction effect. We now turn to additional issues that arise in the reliance on propagation of negative activation.

Propagation of Negative Activations

The DFT_{DDI} approach uses a completely linear dynamical system, in which units can take on positive and negative activations, both of which can propagate via interconnections. This allows the development of closed-form mathematical solutions, which is highly desirable. However, it contrasts with the practice in many connectionist models and other biological neural network models. A basic operating principle of

most of these models is that they make use of some form of non-linearity in the function that determines the output that the units in the network generate based on their inputs. In part this is done because the computations that can be performed by a neural network are severely limited unless there is at least one intermediate layer of non-linear units between inputs and outputs (Rumelhart, Hinton, and McClelland, 1986). For this reason some type of non-linearity is generally supposed as a generic aspect of the framework. Many models are further influenced by the fact that neurons communicate by sending action potentials at some rate that is intrinsically bounded below by 0. To achieve this, they may transform the net input they receive from other units (a linear sum) according to a non-linear function bounded below by 0, or they may propagate the activation value based on the net input only if it is greater than or equal to 0. The latter approach is used widely in the models of Grossberg (1988), in a class of models called interactive activation models (McClelland & Rumelhart, 1981; McClelland & Elman, 1986) and in our leaky competing integrator model of perceptual identification (Usher & McClelland, 2001).

In addition to the neural motivation, the propagation of negative activations can have undesirable consequences in networks with mutual inhibitory connections among units that stand for competing alternatives. The difficulty arises, for example, in the interactive activation model of visual letter and word recognition (McClelland & Rumelhart, 1981), in which there are units for letter-features in each of four display locations, units for letters in each of the same display locations, and units for words that span the four letter positions. Mutually inconsistent units within the same level have mutually inhibitory connections (thus for example units for alternative letters in the first position are mutually inhibitory). In this model, allowing the propagation of negative activations was initially tried, but with deleterious consequences. One problem is that the inhibition of a particular unit results in excitation by negated inhibition of all of the unit's competitors. For example, activation of a word results in inhibition of all other words. If initially all word units are at a resting activation of 0, there is no problem, but as soon as one or a few words receive excitation from the letter level, they then inhibit the vast majority of words, and as their activations go below 0 they all suddenly begin to excite each other due to activation by negated inhibition. They then all become activated together, at which point they then inhibit each other, creating an oscillation in which informational differences in the patterns of activation are quickly eliminated. Note that the problem does not arise if activations below 0 do not propagate. Then units that are excited can inhibit other units and excite units for the letters they contain, but units that are inhibited below 0 do not all send each other activation by negated inhibition.

The propagation of negative activations is not prevented in all neural network models, and we do not wish to suggest that the idea is somehow intrinsically incorrect. However, the same problem with the propagation of negative activations that arises in the interactive activation model would prove problematic for the DFT_{DDI} if it were extended to situations in which there are several similar alternatives all simultaneously competing. In that case the problem of oscillations seen in the interactive activation model would also arise. These considerations, when taken together with the issues noted above, contribute to our suggestion that it may be worth considering whether the phenomena captured by the DFT_{DDI} model could be captured in a

model that does not rely on the distance-dependent propagation of negative activations.

Leaky Competing Accumulators with Loss-Aversion Value-Function

The model we explore here is based on the leaky-competing accumulator model previously introduced (Usher & McClelland, 2001) to account for perceptual identification in situations involving two or more choice alternatives. This model shares many assumptions with the DFT_{DDI} model, including the use of leaky, competing units that integrate intrinsically noisy or stochastic information. Our model was intended as a simplification of a more complex neurophysiological process that captures the dynamics of ensembles of neurons thought to collectively represent psychological variables such as the states of activation of the various alternatives in a choice situation (see, e.g., Usher & Niebur, 1996). To address multi-alternative, multi-attribute choice, we adopt a further assumption incorporated in multi-attribute versions of the DFT (Busemeyer & Diederich, 2002; Diederich, 1997, 2003; Roe et al., 2001) as well as in a previous neural network model for multi-attribute decision-making (Usher & Zakay, 1993). This assumption, whose precursor was also used in Tversky’s (1972) EBA model, involves a stochastic process of switching attention between the attributes of the choice alternatives.⁵ As already shown by Tversky (1972) this assumption can explain the similarity effect. However, our model differs from the DFT_{DDI} in that it follows Tversky and Kahneman (1991) and Tversky and Simonson (1993) in assuming the existence of an asymmetric value-function displaying loss-aversion. The use of such a value function provides explanations for the compromise and attraction effects, avoiding the need to invoke distance dependent activation by negated inhibition. Although our model does use lateral inhibition, activations do not propagate below 0 so there is no boosting by negated inhibition, and the strength of lateral inhibitory interactions are uniform rather than distance-dependent.

In Figure 2, the model is illustrated for situations involving a choice between three alternatives (A1, A2 and A3), characterized by their values on two dimensions (labeled Q for performance quality and E for economy).

The model operates as follows. At each time iteration, one dimension is chosen randomly to be the focus of attention. The input to each of the leaky competing accumulator units is determined by an input pre-processing stage, based on nonlinear transformations of the differences between all pairs of alternatives on the chosen dimension. Thus, unlike in Tversky and Simonson (1993), the loss-aversion value function is applied separately within each dimension.

Pre-processing stage. The characteristics of this stage follow Tversky and Simonson (1993) in assuming that in multi-alternative choice situations, when participants are faced with options that do not provide an explicit reference, they evaluate the options in relation to each other (i.e., each option is being used as a reference point in the evaluation of each other option; the explicit reference situation is addressed below). For

⁵In EBA the attributes are sampled without replacement. We adopt the *sampling with replacement* procedure used by Roe et al (see also, Diederich, 1997, 2003, and Usher & Zakay, 1993).

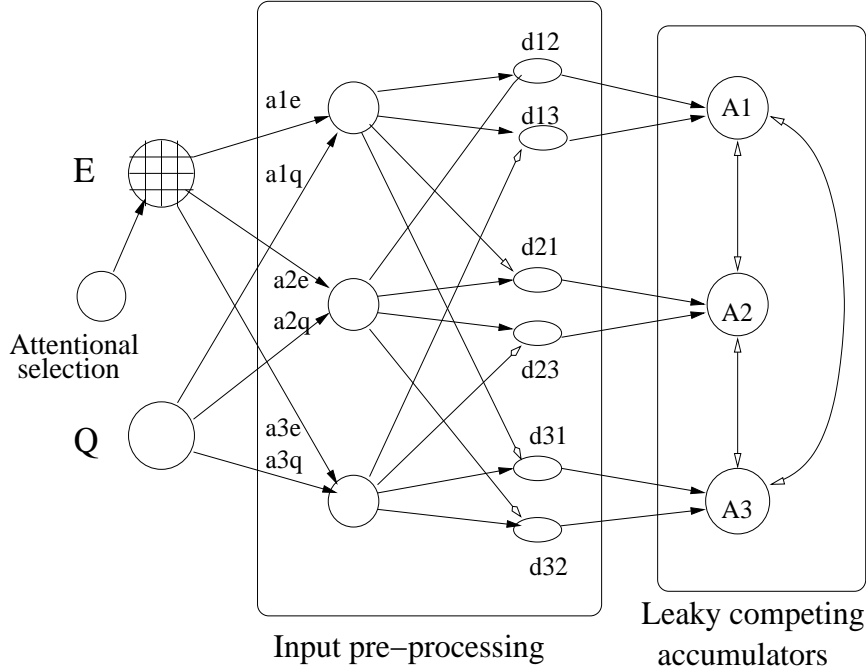


Figure 2: Model scheme for a choice between 3 options characterized by two dimensions, Q and E, respectively. The solid arrows correspond to excitation and the open ones to inhibition. At every time step, an attentional system stochastically selects the activated dimension (Q in this illustration). The input-item units in the second layer represent each option according to its weights on both of the dimensions and project into difference-input units in the 3rd layer (ellipses; together, the 2nd and 3rd layer have the function of input-preprocessing). This layer converts the differences via an asymmetric nonlinear value function before transmitting them to the leaky-competing accumulators, A_i , in the choice layer.

example in the three-alternative case, inputs I_i to the leaking accumulators are governed by these equations:

$$I_1 = V(d_{12}) + V(d_{13}) + I_0 \quad (1)$$

$$I_2 = V(d_{21}) + V(d_{23}) + I_0 \quad (2)$$

$$I_3 = V(d_{31}) + V(d_{32}) + I_0 \quad (3)$$

where d_{ij} is the differential (advantage or disadvantage) of option i relative to option j , computed on the chosen dimension; V is the nonlinear advantage function, and I_0 is a positive constant that can be seen as promoting the available alternatives into the choice set. Without this the input to each accumulator unit would always be negative because of the loss-averse value function. The nonlinear advantage function (Figure 3) is chosen, consistent with Tversky and Kahneman (1991) and Tversky and Simonson (1993), to provide diminishing returns for high gains or losses, and aversion for losses relative to the corresponding gains:

$$V(x) = z(x), x > 0 \quad (4)$$

$$V(x) = -(z(|x|) + [z(|x|)]^2), x < 0 \quad (5)$$

Here $z(x) = \log(1+x)$ is a function whose slope at the origin is unity and decreases monotonically with gains. Notice that, as proposed by Tversky and Simonson (1993), the value function for losses is a convex function of the corresponding gains.⁶ Moreover, as in the graphical displays of the context-advantage function (Tversky & Kahneman, 1991), the value function has a higher slope in the domain of losses than in the domain of gains, providing an advantage for similar options and penalizing dissimilar option pairs (Figure 3). This is the essential component that enables us to account for the attraction, compromise and loss-aversion effects.

We assume that when the options for choice are framed relative to a reference (this may include an option the participant is required to give up in order to choose a new option in its place), the value function is evaluated relative to this reference (Tversky & Kahneman, 1984; 1991). For example, in the case where a previously held (terminating) job must be exchanged for one of two (this generalizes straightforwardly to n-choice) other (available) jobs, we have:

$$I_1 = V(d_{1R}) + I_0 \quad (6)$$

$$I_2 = V(d_{2R}) + I_0 \quad (7)$$

These features make our model similar to the context-dependent advantage model (Tversky & Simonson, 1993). However, instead of obtaining a single preference value for every pair of choices, the gains and losses are estimated on each dimension separately, combining the assumptions of the context-dependent advantage model with that of the EBA model.

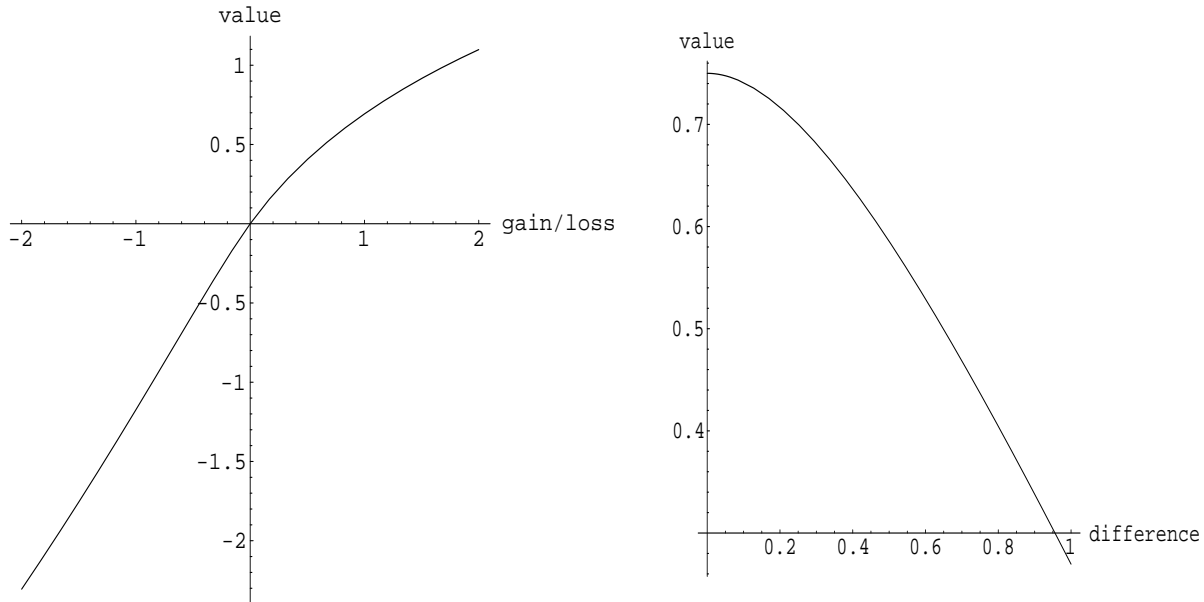


Figure 3: Left: Nonlinear value function, similar with the one used in the reference-dependent model of riskless choice (Tversky & Simonson, 1993). Right: Average input to the model obtained by averaging gains and losses in the value function of A and adding a constant $I_0 = .75$.

⁶Consider a gain of size x and a loss of size $-x$ and the values $V(x)$ and $V(-x)$ of the associated gain and loss. The convex function we use has the property that $V(-x) = f[V(x)]$, where $f(x) = -(x + x^2)$.

Leaky-integration process. The activation values of the leaky competing choice units, A_i , integrate the input subject to decay, according to the following iterative procedure (see Usher and McClelland, 2001, for the differential equation version):

$$A_i(t+1) = \lambda A_i(t) + (1-\lambda)[I_i(t) - \beta \sum_{j \neq i} A_j(t) + \xi_i \cdot(t)] \quad (8)$$

Here λ is the neural decay constant, β is the global inhibition parameter, ξ corresponds to a normally distributed noise term with zero mean and $SD = \sigma$, and I_i corresponds to the inputs as previously indicated. These equations are further supplemented by resetting negative activations to zero. In Usher and McClelland (2001) we show that this is quantitatively indistinguishable from an alternative formulation in which units are allowed to take on negative activations but these activations are not propagated (no negative firing rates).

Details of the Implementation

Option representations. As in DFT_{DDI} we consider sets of options characterized by two attributes (or dimensions). This includes sets of three options to examine the similarity, compromise and attraction effects (Roe et al., 2001), as well as choices between two options relative to a reference to account for loss-aversion situations (Tversky & Kahneman, 1991). The dimensions are scaled within the interval [0,1]. To further simplify, all the options (except for the dominated alternatives, D , R or F) are chosen on a diagonal line, corresponding to equal binary preferences and the weight of (or the time spent on) each of the two attributes is equal. The options A and B are set to (.15, .85) and (.85, .15). The similar options S_e and S_c were set to (.1, .9) and (.2, .8). The compromise option C is (.5, .5). The dominated options are set as follows: D is set to (.1, .8), R to (.05, .85) and F to (.15, .75). For the inferior (but not strictly dominated) option I , several cases are considered with attribute values $(x, .9)$, with different values of $x < .1$ (see Figure 1).

Model parameters. The parameter values used in the simulations are: $\sigma = .2$, $I_0 = .75$. The value of the leak parameter was set to $\lambda = .94$ as in Roe et al (2001). Also, as in that model the value of the inhibition parameter was varied in order to explore its effect on the choice patterns.

Simulation procedure. Simulation sets of 1000 trials were run for the following six scenarios: i) Loss-aversion (status-quo; A, B with A as reference), ii) loss-aversion (high vs low advantage/disadvantage; A, C with S_e as reference), iii) similarity-compromise (A, B, S_c), iv) similarity-extreme (A, B, S_e), v) compromise (A, B, C) and vi) attraction: (A, B, D). We also tested the difference between range and frequency decoys by replacing (in vi) D with R or F , respectively, and we tested the attraction scenario with a choice between A and B , relative to an explicit reference.

The choice fraction, $P_i(t)$ is computed by running the simulation for 500 iterations and measuring the alternative whose activation is the highest at t . This traces the choice probabilities that would arise from the use of an externally controlled stopping rule at each time point t . Because the actual value of t is not known and may be variable, the model's final choice frequencies for a given alternative are obtained by averaging

$P_i(t)$ over the interval $100 < t < 500$, corresponding to the assumption that the choice is precipitated at a random instant between $t = 100$ and $t = 500$; initial transient effects within the first 100 time steps are not included. The basic effects we present are independent of these details, and we provide the full $P_i(t)$ curves where they are informative. Because of the importance of the magnitude of inhibition in the accounts for some of the effects offered by Roe et al (2001), we explicitly consider to what extent the accounts offered in our model depend on the strength of inhibition in the presentation of the results below.

Results and Discussion

Reference effects: loss-aversion. The choice probability for the A-alternative for inhibition in the range (0, .75) is displayed (Figure 4) for the status-quo situation (option A serving as a reference in a choice between A and B), and for the job-situation (with S_e as reference in a choice between A and C).

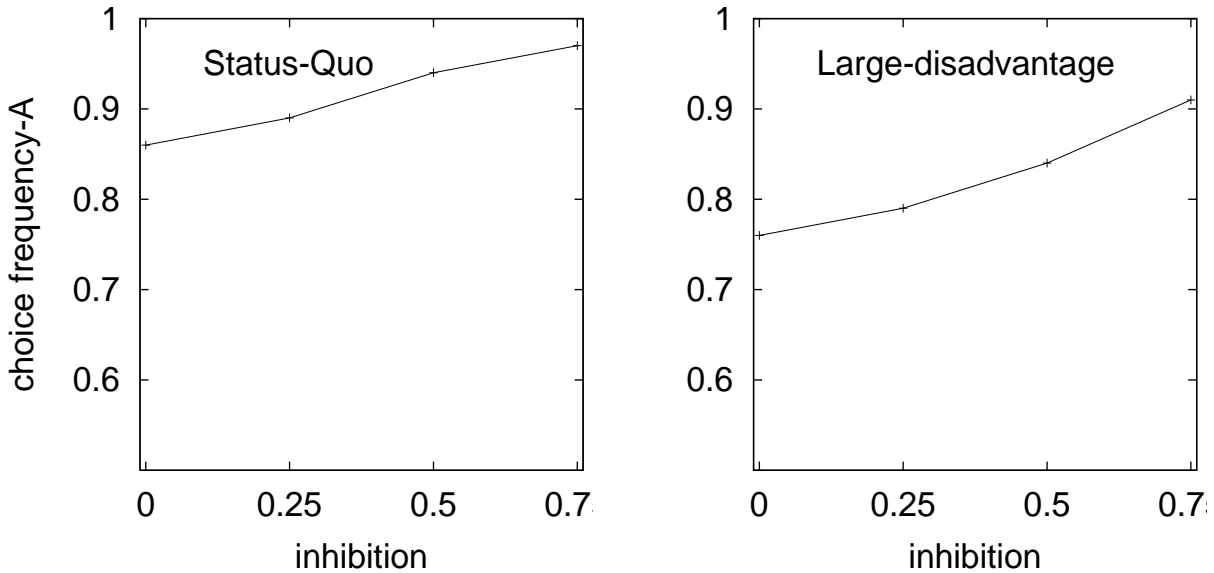


Figure 4: Choice probability for choosing option A (1000 trials per data point), as a function of the inhibition parameter. The y-range is the four panels is different to allow all the pattern of qualitative effects to be seen. Left: status quo effect (A is reference in choice between A and B) Right: the job-scenario, S_e is the reference in choice between A and C (see text).

Consistent with the choice data (Knetch, 1989; Tversky & Kahneman, 1991), we observe a strong bias to choose the option favored by the status quo or to choose the option similar to the reference. (In both situations the choice probability is 50% when the reference is located at mid-distance between the choice options). In the model, the effect is the outcome of the loss-aversion value function, which penalizes the option with a both a large advantage and a large disadvantage relative to the reference. The increase in the level of inhibition has the effect of increasing the competition between the two choice units, amplifying the magnitude of the effect.

Similarity, compromise, and attraction effects. We turn now to the scenarios iii-vi, involving violation of independence, which were accounted for in Roe et al. Here we rely on Equations 1-3, corresponding to a choice among three alternatives without an explicit reference. In Figure 5, the global choice frequencies are shown as a function of the lateral inhibition β for these four scenarios (the simulations were done at $\beta = \{0, .25, .5, .6, .7\}$ and are linearly interpolated at points in between). For a range of inhibition values ($.4 < \beta < .7$), all three effects are obtained.

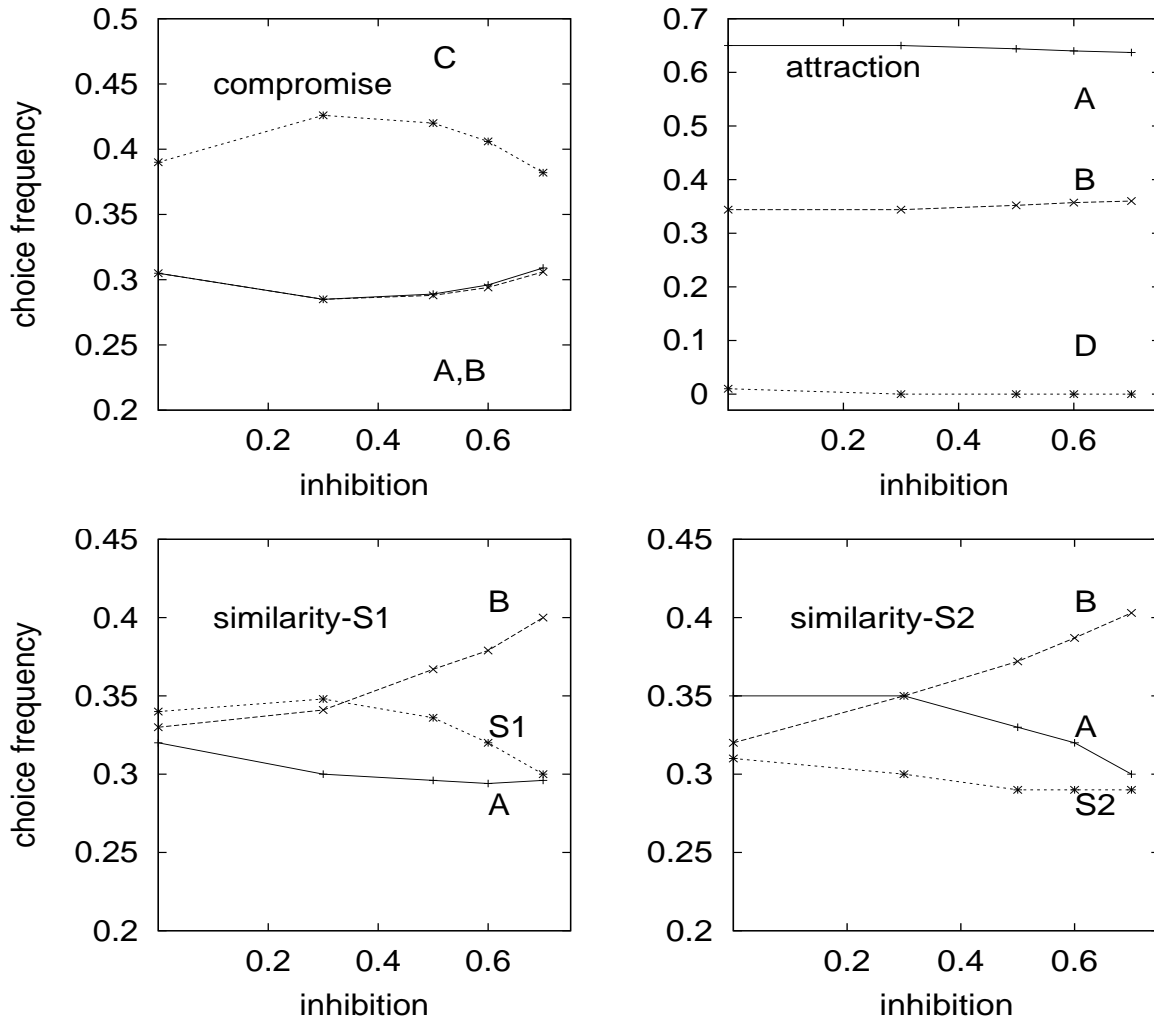


Figure 5: Simulation results (1000 trials per data point). Compromise (A, B, C): the compromise option C wins; attraction (A, B, D): the A alternative (similar to D) wins. Similarity [$(A, B, S_c), (A, B, S_e)$]: the dissimilar alternative B wins.

The explanation of the compromise and attraction effects is a direct outcome of the loss-aversion advantage function, as in the context-advantage model (Tversky & Simonson, 1993). In both conditions the distant options (B in the similarity condition and both A and B in the compromise) are penalized by the asymmetry in the loss-aversion value function. As a result, the option C (having fewer distant alternatives)

is preferred in the compromise condition, and A is preferred over B (which has two distant alternatives as opposed to one for A) in the attraction condition. For the attraction effect, although the dominated option D takes almost no shares, it does attract the choice pattern towards the dominant option A . A similar result (not shown) is obtained if the dominated option is used as a reference according to Equations 4-7, capturing the choice preference for improvements relative to tradeoffs. The degree of inhibition has a nonmonotonic effect on the magnitude of the compromise effect. At low values, the competition between the options has the effect of increasing the choice sensitivity as the inhibition and the leak balance each other (Usher & McClelland, 2001) and therefore enhance the choice in favor of the compromise, while higher levels of inhibition diminish the effect.

The similarity effect is illustrated in the bottom panels. Note that for the similarity effect, there is also a slight sign of a compromise effect, such that A gains a little relative to B and S when it is ‘inside’ S (similarity- S_e) and loses a little when it is ‘outside’ S (similarity- S_c). The explanation of the similarity effect and the effect of inhibition on it is simple. Here while the loss-aversion function penalizes the dissimilar option, B , the correlation between the activations of the similar options A and S (see Figure 7, top panel), help it. As in the EBA model (Tversky, 1972) and in the DFT, the similar options share high activation during the same choice intervals and thus they share their choices. If, for example, the loss-aversion effect is to give the A -option a share of less than 66% for the choice set (A,B,D) , when D is substituted by S , and assuming that A and S are now splitting their shares, a small advantage for the dissimilar option B , results. This advantage is further amplified by the inhibition. As this increases, the two similar options, A and S , compete to a higher degree, to the advantage of the dissimilar option B . Note that the higher degree of competition between A and S arises even though our model does not employ distance dependent inhibition. It occurs in this case because the activation of the similar alternatives covaries as attention switches between dimensions.

Additional dynamic effects can be observed for the choice pattern in the compromise and the attraction conditions. These are illustrated in Figure 6, which shows the choice probabilities for the different alternatives, $P_i(t)$, for choices made at times varying from 0 to 190 iterations of the computer simulation. The left panel shows the evolution of the choice preference in the compromise condition. We can observe that it takes about 30 iteration steps for the compromise option to dominate the choice. This is due to the fact that early on, one or the other of the extremes is likely to dominate but as the activations are integrated, the fluctuations in the extreme options are averaged out leading to an advantage for the compromise. In the attraction condition (right panel), we see that it takes about 10 iterations for the similar option, A , to dominate the dissimilar option, B . Early on, D is sharing some of the choices with A (as with the similarity effect). As the noise is averaged out with integration time, the amount of choices for the dominated option decreases and the similar options comes to dominate the choice. Our model (as well as the DFT) thus predicts the emergence of the compromise effect (after an early stage in which the opposite effect would be obtained) and an enhancement of the attraction effect with time. (In particular, the model predicts that some par-

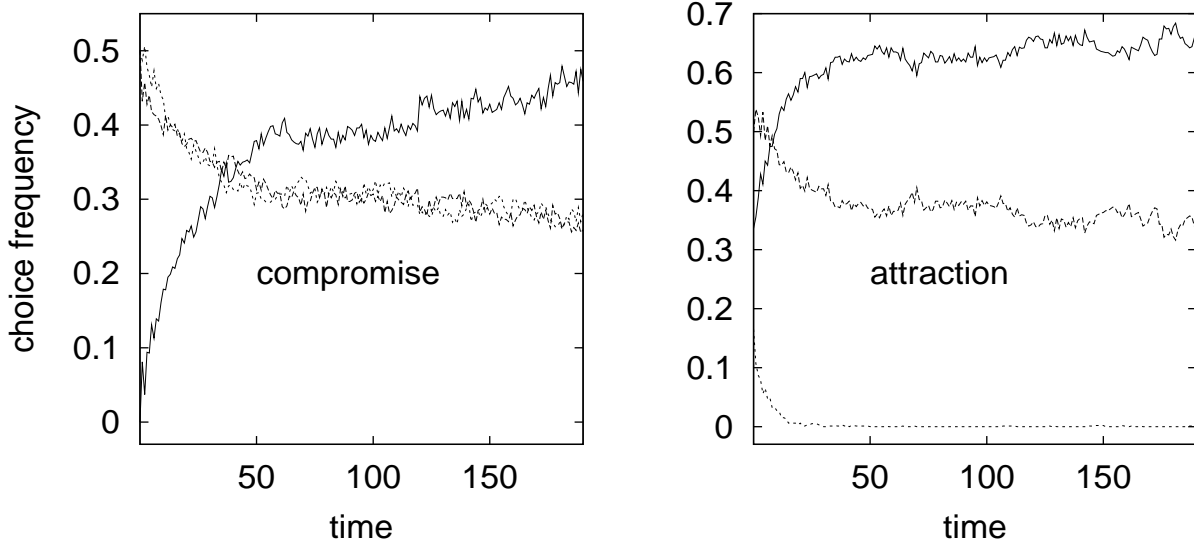


Figure 6: Time dependent choice preference for the compromise effect (left; C-solid line (upper curve), A,B-dashed/dotted lines) and for the attraction effect (right; A-solid line (upper curve), B (dashed-middle), D (dotted-lower)). The inhibition parameter is $\beta = .25$. All other parameters are as above.

x	P(A)	P(I)	P(B)
.10	.33	.29	.37
.08	.49	.13	.37
.06	.58	.05	.36
.05	.61	.03	.36

Table 1: Effects of inferior decoys, I , on the choice between the A and B options.

ticipants will show a reversal of their choices, as the deliberation progresses, in the compromise condition.) Experimental results seem to confirm these predictions, indicating that, as decision makers are encouraged to deliberate longer, the magnitude of the attraction and the compromise effect increases (Simonson, 1989; Dhar, Nowlis & Sherman, 2000).

We considered two additional effects reported in the literature and accounted by the DFT model. First, we tested the impact of the difference between range- and frequency-decoys on the magnitude of the attraction effect. Consistent with Huber et al. (1982) (and as in the Roe et al model), we find a larger attraction effect for the (A, B, R) set [$P(A) = .66, P(B) = .34$] than for the (A, B, F) set [$P(A) = .63, P(B) = .37$]. Second, we examined the impact on the shares of the A and B options of changing the third option from an equal competitor S_e with values $(.1, .9)$ to an inferior but not strictly dominated option, I with values $(x, .9)$, for $x < .1$. The results are presented below:

Consistent with the choice data (Huber et al., 1982) we find that transforming a competitor into an inferior option dramatically alters the shares between the two similar options (A and I) but not the share of the dissimilar option. The DFT model predicts a modest decline in the shares of B (of 5%) for the same

Attraction	P(A)=.87	P(B)=.13	P(D)= .0
Compromise	P(A)=.07	P(B)=.07	P(C)=.84
Similarity	P(A)=.22	P(B)=.12	P(S_c)=.65
Similarity	P(A)=.70	P(B)=.12	P(S_c)=.18

Table 2: Choice probabilities in the model with perfect integration.

change in the shares of A (Roe et al, 2001; Table 4).

The Importance of Leaky Integration

In addition to stochastic alternation of attention, the DFT and our current model also share another important assumption. In both models, the choice is modeled as a sequential sampling process with leakage of information over time. This Ornstein-Uhlenbeck (OU) diffusion process can be distinguished from classical diffusion processes where the samples of information are integrated without loss (e.g., Ratcliff, 1978). The importance of the OU process has been argued both within the DFT framework (Busemeyer & Townsend, 1993; Townsend & Busemeyer, 1995; Diederich, 1997) as applied to decision-making, and in our leaky-competing accumulator model (Usher & McClelland, 2001) for the domain of perceptual choice. Here we explore how the feature of leaky vs perfect integration effects the multi-attribute effects described here. To do this we ran the same simulations, but with the parameter λ set to the value of .999 (corresponding effectively to perfect or lossless integration).

We observe that while the attraction and the compromise effect occur (though at magnitudes which are beyond the range of experimental data), there is a total reversal of the similarity effect (the dissimilar option gets only 12% of the shares).⁷

To help understand the reversal of the similarity effect we show in Figure 7 the activation trajectories for one trial of the simulation for the case of leaky integration ($\lambda = .94$) (top panel) and for the case of perfect integration (bottom panel). We observe that unlike with the leaky integration, where the dissimilar option (dotted line with symbols) has extended time intervals where it dominates the option set, with the perfect integration the dissimilar option is dominated throughout the simulation. This is as a result of the asymmetric value function. The leakage of information is thus essential in accounting for the similarity effect, once a loss-aversion advantage function is assumed. This is because it makes the activation of the choice units dependent on a recency-based temporal window. As the attributes are stochastically sampled, there are time windows where the dissimilar choice unit receives a stronger input (when the supporting attribute is sampled) and this unit makes a recovery and dominates the option-set. With a perfect integration, the advantages and disadvantages that correspond to the sequential sampling of the attributes are integrated and they average out, leading to the advantage of the S_c -option due to the compromise effect.

⁷In a separate set of simulations we tested whether the non-leaky integrator model can account for the effect, when the asymmetry in the value function is diminished. To do this we parametrized the magnitude of this asymmetry by ϵ in the convex function $f(x) = x + \epsilon x^2$. For $\epsilon = .29$ we obtain a relatively small compromise effect (of 4%). Even in this situation, however, the perfect integrator model is unable to account for the similarity effect.

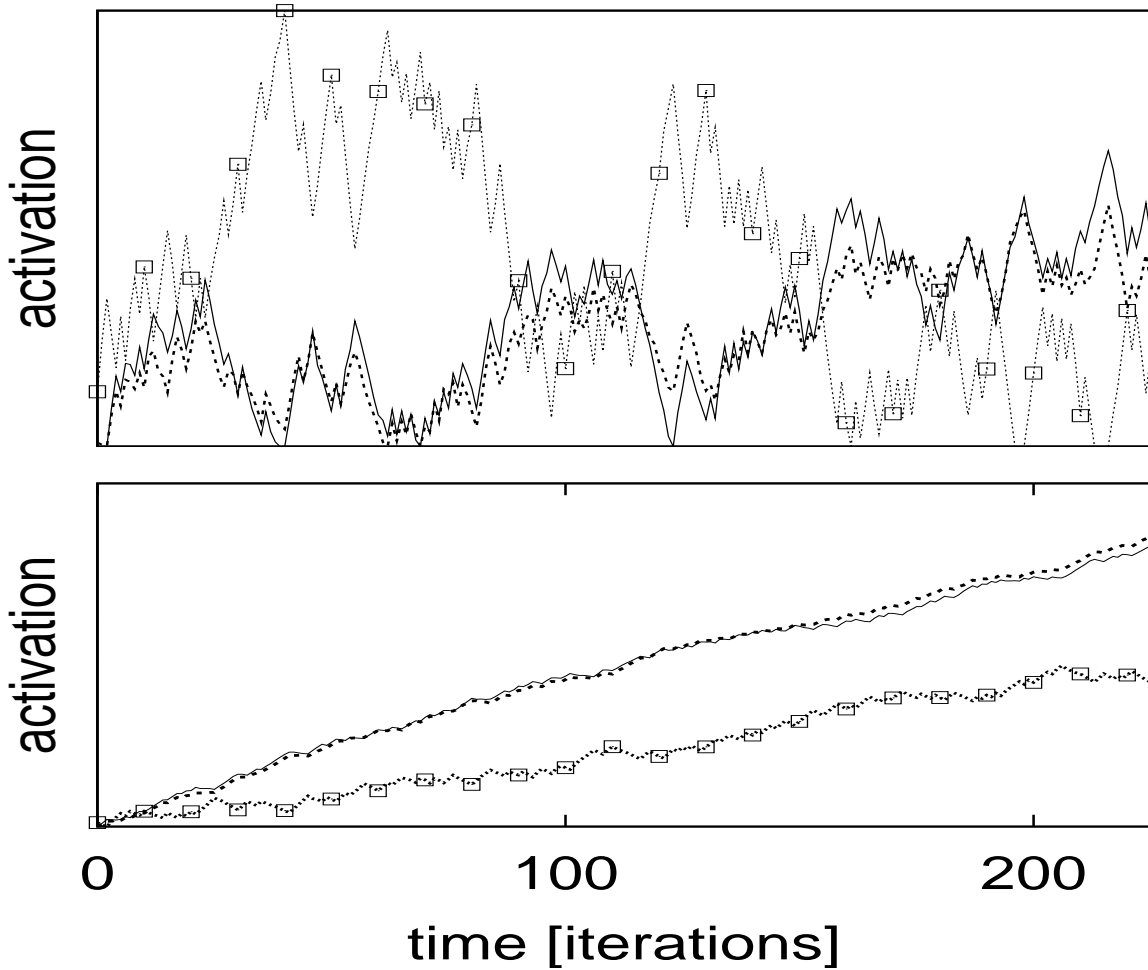


Figure 7: Activation trajectories for one trial in the similarity condition for the leaky integrator with competition (top) and for the perfect integrator (bottom). A: solid line, B: dotted line with symbols, S_c : bold dotted line.

Evaluations and New Predictions

We have proposed a model which shares a number of important assumptions with the DFT framework. These include leaky integration and lateral inhibition that triggers choice competition. We also share with the DFT model the stochastic sampling of attributes (see also, Diederich, 1997; Busemeyer & Diederich, 1999; 2003; Usher & Zakay, 1993). The models make different assumptions, however, about the principles of processing relating to inhibition. Roe et al. use distant-dependent inhibition and rely on activation by negated inhibition, whereas in our model inhibition is distance independent and there is no propagation through inhibitory connections when activations go below 0. Instead, we rely on the asymmetric value functions, where losses are a convex function of gains (Tversky & Simonson, 1993), which have played a

central role in previous work in decision-making. The inclusion of loss-aversion in the model enables us to account to a large amount of data, such as the status-quo and other reference effects, which motivated Tversky and colleagues to rely on this mechanism, in their decision-making theory.

Like the DFT_{DDI} , our model can account for violations of ‘independence of irrelevant alternatives’ (i.e., similarity, attraction and compromise) which have challenged other theories of multiattribute decision-making. In addition, the model, as well as the DFT_{DDI} , accounts for some more subtle effects, such as increased attraction effect with range- rather than frequency-decoys and the preserved shares of the competitor B, when the option similar to A, S_e is transformed into an inferior option (I). These properties are largely shared with the DFT_{DDI} model. The models also make the same prediction regarding the increase in the magnitude of compromise effects with RT and choice reversals under time pressure.

Despite these similarities, the way in which the DFT (as implemented in Roe et al., 2001) and the present model account for many of the effects is not the same, and this is reflected in a number of differences and diverging predictions. The main differences concerns the way in which the attraction and the compromise effects are explained.

Consider first the attraction effect. While in Roe et al. (2001), the dominating option (A) wins due to an additional boost from the similar dominated option, in our model, the effect is due to the cost suffered by the dissimilar option (B), which is penalized by the asymmetric value function. Our model predicts therefore that the shares of the B-option are almost preserved when a competitive option such as S_c is transformed into a dominated option such as D or F; since B is almost equidistant relative to S_c , F and D, its shares are preserved and the attraction is due only to a redistribution of the shares between the two similar options: $P(B|A, B, S_c) = .38$; $P(B|A, B, F) = .37$; $P(B|A, B, D) = .36$. In DFT_{DDI} , however, transforming the competitor option into a dominated option generates a specific boosting for the activation of the similar option, A. This has the effect that the shares of the dissimilar option are diminished to a larger extent [approximately 13% in Roe et al. (2001)]. Experimental studies by Huber et al. (1982) have reported that the shares of the B-competitor is not affected by transforming S_e into an inferior option I. As we saw, both our and the DFT model were able to account for those results, although the preservation is within 1% in the results we presented above, compared with 5% in Roe et al. (2001; Table 2). As the experimental precision may not suffice to test this small difference in the models’ predictions, future studies should focus on choices for options sets (A,B,S) and (A,B,D), where the difference between the predictions is higher, as a result of the fact that D is strictly dominated by A (inferior on both dimensions).

A more fundamental difference between the models is their account of the compromise effect. In our model, the extreme options are penalized by the value function to the benefit of the compromise. In the DFT model, on the other hand, the effect is not driven by differential levels of activation (as the attraction effect) but by correlations due to the local inhibition: the activation of the extremes are correlated in time because they both compete with the compromise. Although both mechanisms account for the compromise

d	.15	.25	.35
P(C)	.33	.40	.42

Table 3: Dependency of the compromise effect on the distance between the options

effect, the correlation mechanism is weaker relative to the boost of activation. This makes the compromise effect of only 4% ($P(C)=.37$) (in Roe et. al (2001), relative to a large attraction effect of 19%). In the model we presented, the magnitude of the compromise effect is larger (about 10%), which is more consistent with the choice data (Simonson, 1989).

Moreover, due to their different nature, the two types of mechanism lead to several qualitative differences in their predictions for new choice situations. Consider first the impact of the distance between the options on the magnitude of the compromise effect. Since the anticorrelations in the DFT_{DDI} are driven by lateral inhibition that decays with distance, the effect should decrease with distance. In our model, on the other hand, the loss aversion increases with distance (Figure 3). As a result we find that the compromise effect shows an increasing relationship. To show this we symmetrically changed the distance, d of the extremes A and B , on each attribute, from the compromise C , from .35 (in the previous simulations) to .25 and .15. The results are shown below:

(This simulation corresponds to an inhibition $\beta = .5$. Other β values yield similar results, e.g. $\beta = .6$, gives $P(C)$ equal to .35, .41, .41 for $d = .15, .25, .35$, respectively.)

Second, future experiments could directly test the correlation hypothesis. Consider for example a situation where a participant chooses one of the extremes, say A , following a response signal at t . According to the correlation hypothesis, the option with the next highest activation at t is the other extreme, B . To test this, one could carry out an experiment in which, on a subset of trials, the choice alternative A is declared unavailable at the instant that it is chosen, and the subject must then make a second speeded choice. Assuming that the subject selects the alternative that is next most active at the same instant as the first selection, the DFT model should predict that for speeded choices, $P(B|A) > P(C|A)$, while the converse is predicted in our model. Finally, it may also be possible to test the correlation hypothesis without a second response by comparing the RT for choices elicited by a response signal for compromise versus extreme options. Under the assumption that the time to resolve the choice is larger for options whose activation values (at the moment when the response signal is received) are similar, one should expect longer RT when either of the correlated options, A or B , is chosen, than when alternative C is chosen.

Conclusion

We have extended our leaky competing accumulator model of perceptual choice to address preferential choice situations, incorporating attentional switching between attributes (following Roe et al, 2001) and loss aversion. With these extensions we have been able to offer an account for several effects that have been

captured within Decision Field Theory by relying on distant-dependent activation by negated inhibition. We do not wish to suggest in any way that the overall decision field theory should be rejected. DFT models have been used to account for many important effects in decision making, such as violations of stochastic dominance and effects of time pressure (Diederich & Busemeyer, 1999; Diederich, 2003), and our model, which has been successfully applied to many phenomena in perceptual choice, is in many ways very similar to the Decision Field Theory. For these reasons, we do not view our model as a competitor to the DFT. Instead, we view it as suggesting some constructive amendments to the DFT framework. We have proposed that the use of distance dependent activation by negated inhibition should be replaced with an explicit reliance on the principle of loss aversion. Although both of these alternative mechanisms can account for basic aspects of the violation of independence effects, the magnitude of the effects may favor our approach. Moreover, we have demonstrated that all these effects, as well as the status-quo effect and two other effects arising when an explicit reference is provided, can be accounted for with the use of a loss-averse value function. It remains to be seen whether a similarly adequate account can be achieved within the DFT with a specified monotonically decaying distance function. We have also suggested that it may be useful to incorporate a non-linearity of the kind employed in many neural network models to avoid undesirable consequences that can arise from activation by negated inhibition when there are many suppressed alternatives. In sum, our leaky competing accumulator model with loss aversion can be viewed as a version of the DFT, incorporating loss aversion and truncation of activation of activations at 0 instead of distant-dependent inhibition and propagation of negative activations.

While our proposed model can be seen as falling within the same overall framework as decision field theory, the processes that enable it to account for choice patterns in decision-making are different in important ways from the processes that take place in the model proposed by Roe et al (2001). In addition to the differences noted above, the two models make several distinct empirical predictions. Future tests of these predictions, whichever way they turn out, will enhance our understanding of the dynamics of decision making, and will contribute to the ongoing process of uncovering the principles of human decision making.

Author Note

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